

Texture Modeling: Self-Similar Gaussian Fields and Monogenic Signal

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Stochastic Geometry Days

Introduction

Goal: Texture modeling and analysis

• Exemplar-based texture synthesis



• Medical diagnostic: e.g. difference between dense and fatty breast tissue¹



Self-similar random fields using the monogenic signal: Riesz transform.

¹BIRADS database

1. Self-similar Gaussian random fields

2. Monogenic signal and multiscale analysis

3. Monogenic parameters for anisotropy and self-similarity estimation

Harmonizable random fields with stationary increments

Harmonizable random fields with stationary increments

Given W an isotropic complex Gaussian measure and f a spectral density function, the random field defined for all $x \in \mathbb{R}^2$, by

$$X(x) := \Re\left(\int [e^{-ix\cdot\xi} - 1]\sqrt{f(\xi)}W(d\xi)
ight)$$

is a Gaussian random field with stationary increments, meaning that

$$\forall x_0 \in \mathbb{R}^2, \{X(x+x_0) - X(x); x \in \mathbb{R}^2\} \stackrel{d}{=} \{X(x); x \in \mathbb{R}^2\}.$$

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Given a function $u: \mathbb{R}^2 \to \mathbb{R}$ such that $|\widehat{u}(\xi)| \leq C \min(1, |\xi|)$, define the generalized field

$$\langle X, u \rangle := \Re \left(\int_{\mathbb{R}^2} \widehat{u}(\xi) \sqrt{f(\xi)} W(d\xi) \right).$$

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Then, $\operatorname{Cov}(\langle X, u \rangle, \langle X, v \rangle) = \Re \left(\int_{\mathbb{R}^2} \hat{u}(\xi) \hat{v}(\xi) f(\xi) d\xi \right)$ and for X a Gaussian random field with stationary increment,

$$\langle X, u \rangle \sim \mathcal{N}\left(0, \int_{\mathbb{R}^2} |\widehat{u}(\xi)|^2 f(\xi) d\xi\right).$$

Self-similar random field

For $H \in (0, 1)$ and a spectral density $f : \xi \mapsto t\left(\frac{\xi}{|\xi|}\right) |\xi|^{-2H-2}$, with $t \in L^1(S^1)$ is defined on the unit sphere, even and positive, such that $f \in L^1(\mathbb{R}^2, \min(1, |\xi|^2 d\xi))$. Then, the random field X associated to f is self-similar of order H, meaning that

$$\{X(\lambda x); x \in \mathbb{R}^2\} \stackrel{d}{=} \lambda^H \{X(x); x \in \mathbb{R}^2\}.$$

² Biermé, Moisan, Richard, A Turning-Band Method for the Simulation of Anisotropic Fractional Brownian Fields, 2015

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Example: Elementary fields² Consider $\delta \in (0, \frac{\pi}{2}]$ and $t_{\delta}(\alpha) = 1_{|\alpha| \le \delta}$ for $\alpha \in (-\frac{\pi}{2}, \frac{\pi}{2}]$. For $\delta = \frac{\pi}{2}$, X is the isotropic fractional Brownian field.



 2 Biermé, Moisan, Richard, A Turning-Band Method for the Simulation of Anisotropic Fractional Brownian Fields, 2015

Riesz transforms³ Given a signal $s \in L^2(\mathbb{R}^2)$, the Riesz transforms are defined, for k = 1, 2 by

$$\mathcal{R}_{k}(s)(x) = \frac{1}{2\pi} \lim_{\varepsilon \to 0} \int_{\mathbb{R}^{2} \setminus B_{\varepsilon}(x)} \frac{x_{k} - y_{k}}{|x - y|^{3}} s(y) dy.$$
(1)

Then,

$$\widehat{\mathcal{R}_k(s)}(\xi) = -i \frac{\xi_k}{|\xi|} \widehat{s}(\xi) ext{ for } \xi \in \mathbb{R}^2.$$

The associated monogenic signal $s_M(x)$ is a signal in \mathbb{R}^3

$$s_M(x) = \begin{bmatrix} s(x) \\ \mathcal{R}_1(s)(x) \\ \mathcal{R}_2(s)(x) \end{bmatrix}$$

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The associated **monogenic signal** $s_M(x)$ is a signal in \mathbb{R}^3 and can also be characterized by its spherical coordinates:

$$s_{M}(x) = \begin{bmatrix} s(x) \\ \mathcal{R}_{1}(s)(x) \\ \mathcal{R}_{2}(s)(x) \end{bmatrix} = \begin{bmatrix} A(x)\cos\varphi(x) \\ A(x)\sin\varphi(x)\cos\theta(x) \\ A(x)\sin\varphi(x)\sin\theta(x) \end{bmatrix},$$

with $A(x) \in \mathbb{R}^+$ the amplitude of the monogenic signal, $\varphi(x) \in [0, \pi)$ its phase and $\theta(x) \in [-\pi, \pi)$ its orientation.

³M. Felsberg et G. Sommer, The monogenic signal, 2001

Advantages of the Riesz transform:



- Similar to the Gradient operator: detection of contours and orientations
- Very easy to compute in the Fourier domain
- Adapted to a multiscale analysis⁴

⁴ R. Soulard et P. Carré, *Characterization of color images with multiscale monogenic maxima*, 2018. Images from R. Soulard's website.

Monogenic signal: Given a Gaussian random field X and a function $u \in S_0(\mathbb{R}^2)$, the monogenic signal is

$$MX(u) = \langle X, u \rangle_M = \begin{bmatrix} \langle X, u \rangle \\ \langle \mathcal{R}_1 X, u \rangle \\ \langle \mathcal{R}_2 X, u \rangle \end{bmatrix} = (\langle X, u \rangle, \mathcal{R}_X(u)).$$

It is a Gaussian vector and its covariance function is

$$\mathcal{C}_{MX}(u,v) := \mathbb{E}\left(MX(u)MX(v)^*\right) = \Re \int \begin{pmatrix} 1 & i\frac{\xi_1}{|\xi|} & i\frac{\xi_2}{|\xi|} \\ -i\frac{\xi_1}{|\xi|} & \frac{\xi_1}{|\xi|^2} & \frac{\xi_1\xi_2}{|\xi|^2} \\ -i\frac{\xi_2}{|\xi|} & \frac{\xi_1\xi_2}{|\xi|^2} & \frac{\xi_1\xi_2}{|\xi|^2} \end{pmatrix} \hat{u}(\xi)\overline{\hat{v}(\xi)}f(\xi)d\xi.$$

We consider a multiscale representation of the initial random field using a function u, such that $u \in S_0(\mathbb{R}^2)$, with $\int_{\mathbb{R}^2} u(x) dx = 1$ and $u_j(x) = 2^{-j}u(2^{-j}x)$.

Note that in our experiments, we used an undecimated filter bank, given by

$$\begin{cases} \widehat{G}_{1}(\xi) = 1 - e^{-|\xi|^{2}/2}, \\ \widehat{G}_{j}(\xi) = \widehat{G}_{1}(2^{j-1}\xi), \\ \widehat{H}_{j}(\xi) = \sqrt{1 - \widehat{G}_{j}(\xi)^{2}}. \end{cases}$$
(2)

At each scale j, we consider the Riesz transform of the filtered random field

 $\mathcal{R}_{X}(u_{j}) = \left(\langle \mathcal{R}_{1}X, u_{j} \rangle, \langle \mathcal{R}_{2}X, u_{j} \rangle \right),$

and we denote $\tau_x u_i$ the translation of u_i in x, used to evaluate the random field in x.

Proposition

Consider $(\delta, H) \in (0, \pi/2] \times (0, 1)$ and $u \in S_0(\mathbb{R}^2)$ a radial function. If X is an elementary field with spectral density $f_X(\xi) = t_{\delta}(\xi/|\xi|)|\xi|^{-2H-2}$ then $(MX(\tau_x u))_{x \in \mathbb{Z}^2}$ is a centered stationary Gaussian field such that for all $x \in \mathbb{Z}^2$,

$$MX(\tau_{X}u) \stackrel{d}{=} \sqrt{c_{X}(u)} D_{\delta}Z,$$

where

•
$$c_X(u) = \operatorname{Var}(\langle X, u \rangle) = \int_{\mathbb{R}^2} |\widehat{u}(\xi)|^2 f(\xi) d\xi,$$

• $D_{\delta} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \sqrt{\frac{1}{2} + \frac{\sin(2\delta)}{4\delta}} & 0 \\ 0 & 0 & \sqrt{\frac{1}{2} - \frac{\sin(2\delta)}{4\delta}} \end{pmatrix}$

• $Z \sim \mathcal{N}(0, I_3)$.

Moreover, for a given scale *j*,

$$(MX(\tau_{x}u_{j}))_{x\in\mathbb{Z}^{2}}\stackrel{d}{=}2^{j(H+1)}(MX(\tau_{x}u))_{x\in\mathbb{Z}^{2}}.$$

Riesz structure tensor⁵:

$$J_X(u_j) := \mathbb{E}\left(\mathcal{R}X(u_j)\mathcal{R}X(u_j)^*\right),$$

with $(\lambda^+(u_j), \lambda^-(u_j))$ its largest and smallest eigenvalues.

Coherence index:

$$\chi_X(u_j) = \frac{\lambda^+(u_j) - \lambda^-(u_j)}{\lambda^+(u_j) + \lambda^-(u_j)} \in [0, 1),$$

allows to measure the directional anisotropy.

⁵K. Polisano. Modélisation de textures anisotropes par la transformée en ondelettes monogéniques, 2017

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For an elementary field,

$$\lambda^{\pm}(u_j) = 2^{j(2H+2)}\lambda^{\pm}(u) \text{ and } \chi_X(u_j) = \frac{\sin(2\delta)}{2\delta}.$$
(3)

⁵K. Polisano. Modélisation de textures anisotropes par la transformée en ondelettes monogéniques, 2017

Proposition • $(A(\tau_{x}u), \theta(\tau_{x}u), \varphi(\tau_{x}u))_{x \in \mathbb{Z}^{2}}$ is a stationary field.

• Orientation distribution: $\theta(u)$ is independent of $(A(u), \varphi(u))$ and follows an offset normal distribution whose probability density function is π -periodic and given by

$$t\mapsto \frac{\sqrt{1-\chi_X(u)^2}}{2\pi(1-\chi_X(u)\cos(2t))},$$

where $\chi_X(u) \in [0,1)$ is the coherence index.

• Isotropic case: In the isotropic case, if $\delta = \pi/2$, $\theta(u)$ follows a uniform distribution on $(-\pi, \pi)$ and the density function of the phase $\varphi(u)$ is given by

$$\phi \mapsto \frac{|\sin(\phi)|}{(1+\sin(\phi)^2)^{3/2}} \mathbb{1}_{(0,\pi)}(\phi).$$

Monogenic representation of an elementary field



Elementary field with $H = 0.5, \delta = \pi/2$.

Monogenic representation of an elementary field



Monogenic representation of an elementary field



Empirical estimator of the structure tensor:

$$J_j^{\mathsf{emp}} = \frac{1}{N^2} \sum_{x \in G} \mathcal{R}X(\tau_x u_j) \mathcal{R}X(\tau_x u_j)^*,$$

with $(\lambda^{+emp}(u_j), \lambda^{-emp}(u_j))$ its largest and smallest eigenvalues.

Proposition J_i^{emp} is an unbiased estimator and

$$J_{j}^{\mathsf{emp}} \xrightarrow[N \to \infty]{a.s.} J_{X}(u_{j}).$$

$$\tag{4}$$

Besides, $\lambda_j^{\pm emp} \xrightarrow[N \to \infty]{a.s.} \lambda_j^{\pm}$.

Inference using the structure tensor - Coherence index





Coherence index estimation, for 1000 realizations, depending on a) the scale of the monogenic representation j and the degree of anisotropy δ , with H = 0.5 and b) the degree of anisotropy and H, with j = 3.

Inference using the structure tensor - Hurst index

$$\lambda^{\pm}(u_j) = 2^{j(2H+2)}\lambda^{\pm}(u)$$



Estimation of H, obtained by the eigenvalues $\lambda_j^{\pm emp}$ from $J_X(u_j)$ (a). Dotted lines are computed by linear regression and provide an estimator of the Hurst parameter H (b).

Inference using the monogenic signal

Proposition

Squared amplitude: $A(u_j)^2 = \langle X, u_j \rangle^2 + |\mathcal{R}X(u_j)|^2$ and $A(u_j)^2 \stackrel{d}{=} c_X(u_j)A^2$, with $A^2 = |D_{\delta}Z|^2$ for $Z \sim \mathcal{N}(0, I_3)$, D_{δ} and

$$c_X(u_j) = \operatorname{Var}(\langle X, u_j \rangle) = 2^{j(2H+2)} \operatorname{Var}(\langle X, u \rangle).$$

The estimator $V^{ ext{emp}}_j = rac{1}{N^2} \sum\limits_{x \in G} |MX(au_x u_j)|^2$ is unbiased and

$$V_j^{\operatorname{emp}} \xrightarrow[N \to \infty]{a.s.} \mathbb{E} \left(|MX(u_j)|^2 \right).$$

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- Two methods based on the Riesz transform to estimate the parameters of elementary fields.
- Using the full monogenic signal seems to produce more stable estimators.

Perspectives:

- Study further the statistical properties of these estimators
- Get similar results for larger categories of self-similar random fields
- Extend to color textures ie multivariate random fields

⁶C.L., H. Biermé, C. Lacaux, P. Carré, *Modélisation de Textures : Champs Gaussiens Autosimilaires et Signal Monogène*, 2023 (accepted)